

LMH6734 Single Supply, Ultra High-Speed, Triple Selectable Gain Buffer

Check for Samples: [LMH6734](#)

FEATURES

- (Typical Values Unless Otherwise Specified.)
- Supply Range 3V to 12V Single Supply
- Supply Range $\pm 1.5\text{V}$ to $\pm 6\text{V}$ Split Supply
- 925 MHz -3 dB Small Signal Bandwidth ($A_V = +1$, $V_S = \pm 5\text{V}$)
- 650 MHz -3 dB Small Signal Bandwidth ($A_V = +2$, $V_S = 5\text{V}$)
- Low Supply Current (5.5 mA per op amp, $V_S = 5\text{V}$)
- 2.1 nV/ $\sqrt{\text{Hz}}$ Input Noise Voltage
- 3750 V/ μs Slew Rate ($V_S = \pm 5\text{V}$)
- 70 mA Linear Output Current ($A_V = +2$, $V_S = \pm 5\text{V}$)
- Input Range and Output Swing to 1V from each Supply Rail

APPLICATIONS

- HDTV Component Video Driver
- CAT5 Component Video Driver
- High Resolution Projectors
- Wide Dynamic Range IF Amp
- DDS Post-amps
- Wideband Inverting Summer
- Line Driver

DESCRIPTION

The LMH6734 is a high speed monolithic selectable gain buffer designed specifically for ultra high resolution video systems as well as wide dynamic range systems requiring exceptional signal fidelity. Benefiting from TI's current feedback architecture, the LMH6734 offers gains of -1 , $+1$ and $+2$. At a gain of $+2$ the LMH6734 supports ultra high resolution video systems with a 560 MHz $2 V_{PP} 3$ dB bandwidth. With this large signal bandwidth and 2.1 nV/ $\sqrt{\text{Hz}}$ of input referred noise, the LMH6734 is ideal for driving component video over CAT5 cable up to 200 ft without frequency and gain equalization. The LMH6734 is offered in a space saving 16-Pin SSOP package.

Connection Diagram

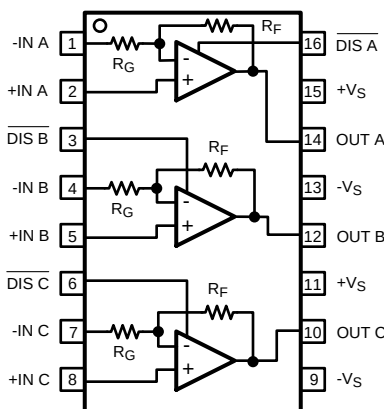


Figure 1. 16-Pin SSOP - Top View
 $R_F = R_G = 327\Omega$



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings⁽¹⁾⁽²⁾

ESD Tolerance ⁽³⁾	Human Body Model	2000V
	Machine Model	200V
Supply Voltage ($V^+ - V^-$)		13.2V
I_{OUT}		See ⁽⁴⁾
Common Mode Input Voltage		$\pm V_{CC}$
Maximum Junction Temperature		+150°C
Storage Temperature Range		-65°C to +150°C
Soldering Information	Infrared or Convection (20 sec.)	235°C
	Wave Soldering (10 sec.)	260°C
Storage Temperature Range		-65°C to +150°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics tables.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).
- (4) The maximum output current (I_{OUT}) is determined by device power dissipation limitations. See the [POWER DISSIPATION](#) section of the Application Information for more details.

Operating Ratings⁽¹⁾

Temperature Range ⁽²⁾	-40°C to +85°C	
Supply Voltage ($V^+ - V^-$)	3V to 12V	
Thermal Resistance		
Package	(θ_{JC})	(θ_{JA})
16-Pin SSOP	36°C/W	120°C/W

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics tables.
- (2) The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

5V Electrical Characteristics⁽¹⁾

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ\text{C}$, $V^+ = +5\text{V}$, $A_V = +2$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ⁽²⁾	Typ ⁽³⁾	Max ⁽²⁾	Units
Frequency Domain Performance						
UGBW	-3 dB Bandwidth	Unity Gain, $V_{OUT} = 200 \text{ mV}_{PP}$		870		MHz
SSBW	-3 dB Bandwidth	$V_{OUT} = 200 \text{ mV}_{PP}$, $R_L = 100\Omega$		650		MHz
SSBW		$V_{OUT} = 200 \text{ mV}_{PP}$, $R_L = 150\Omega$		685		
LSBW		$V_{OUT} = 2 \text{ V}_{PP}$		480		
0.1 dB BW	0.1 dB Gain Flatness	$V_{OUT} = 200 \text{ mV}_{PP}$		130		MHz

- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$. No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self heating where $T_J > T_A$. See [Application Information](#) for information on temperature de-rating of this device. Min/Max ratings are based on product characterization and simulation. Individual parameters are tested as noted.
- (2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlation using Statistical Quality Control (SQC) methods.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.

5V Electrical Characteristics⁽¹⁾ (continued)

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ\text{C}$, $V^+ = +5\text{V}$, $A_V = +2$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ⁽²⁾	Typ ⁽³⁾	Max ⁽²⁾	Units
Time Domain Response						
TRS	Rise and Fall Time (10% to 90%)	2V Step		0.7		ns
SR	Slew Rate	2V Step		1900		V/μs
t _s	Settling Time to 0.1%	2V Step		10		ns
t _e	Enable Time	From $\overline{\text{Disable}}$ = Rising Edge		10		ns
t _d	Disable Time	From $\overline{\text{Disable}}$ = Falling Edge		15		ns
Distortion						
HD2L	2 nd Harmonic Distortion	2 V _{PP} , 10 MHz		−63		dBc
HD3L	3 rd Harmonic Distortion	2 V _{PP} , 10 MHz		−73		dBc
Equivalent Input Noise						
V _N	Non-Inverting Voltage	>10 MHz		2.1		nV/√Hz
I _{CN}	Inverting Current	>10 MHz		18.6		pA/√Hz
N _{CN}	Non-Inverting Current	>10 MHz		26.9		pA/√Hz
Video Performance						
DG	Differential Gain	4.43 MHz, R _L = 150Ω		0.03		%
DP	Differential Phase	4.43 MHz, R _L = 150Ω		0.025		deg
Static, DC Performance						
V _{IO}	Input Offset Voltage			0.4	2.0 2.5	mV
I _{BN}	Input Bias Current	Non-Inverting	2	16.7	28 32	μA
PSRR	Power Supply Rejection Ratio	+PSRR	59 59	61		dB
		−PSRR	58 56	61		
CMRR	Common Mode Rejection Ratio		52 52	54.5		dB
XTLK	Crosstalk	Input Referred, f = 10 MHz, Drive Channels A, C and Measure Channel B		−80		dB
I _{CC}	Supply Current	All three amps Enabled, No Load	15 15	16.7	18 19	mA
	Supply Current Disabled V ⁺	R _L = ∞		1.54	1.8	mA
	Supply Current Disabled V [−]	R _L = ∞		0.75	1.8	mA
	Gain Error	R _L = ∞		0.2	1.25	%
	Gain	A _V = +2	1.975	1.996	2.025	V/V
		A _V = +1		0.998		
		A _V = −1	−0.9875	−0.998	−1.0125	
Miscellaneous Performance						
R _{IN} ⁺	Non-Inverting Input Resistance			200		kΩ
C _{IN} ⁺	Non-Inverting Input Capacitance			1		pF
R _O	Output Impedance	DC		0.05		Ω
V _O	Output Voltage Range	R _L = 100Ω	1.25-3.75 1.3-3.7	1.12-3.88		V
		R _L = ∞	1.11-3.89 1.15-3.85	1.03-3.97		
CMIR	Input Range	Driving input +INA, CMRR > 40 dB	1.1-3.9 1.2-3.8	1.0-4.0		V

5V Electrical Characteristics⁽¹⁾ (continued)

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ\text{C}$, $V^+ = +5\text{V}$, $A_V = +2$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ⁽²⁾	Typ ⁽³⁾	Max ⁽²⁾	Units
I_O	Linear Output Current	$V_{IN} = 0\text{V}$, $V_{OUT} < \pm 42\text{ mV}^{(4)}$	± 50	± 60		mA
I_{SC}	Short Circuit Current	$V_{IN} = 2\text{V}$ Output Shorted to Ground ⁽⁵⁾		170		mA
I_{IH}	Disable Pin Bias Current High	$\overline{\text{Disable}} = \text{Pin} = V^+$		-72		μA
I_{IL}	Disable Pin Bias Current Low	$\overline{\text{Disable}} = \text{Pin} = 0\text{V}$		-360		μA
V_{DMAX}	Voltage for Disable	$\overline{\text{Disable}} = \text{Pin} \leq V_{DMAX}$		3.2		V
V_{DMIN}	Voltage for Enable	$\overline{\text{Disable}} = \text{Pin} \geq V_{DMIN}$		3.6		V

- (4) The maximum output current (I_{OUT}) is determined by device power dissipation limitations. See the [POWER DISSIPATION](#) section of the Application Information for more details.
- (5) Short circuit current should be limited in duration to no more than 10 seconds. See the [POWER DISSIPATION](#) section of the Application Information for more details.

$\pm 5\text{V}$ Electrical Characteristics⁽¹⁾

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ\text{C}$, $V^+ = +5\text{V}$, $V^- = -5\text{V}$, $A_V = +2$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ⁽²⁾	Typ ⁽³⁾	Max ⁽²⁾	Units
Frequency Domain Performance						
UGBW	-3 dB Bandwidth	Unity Gain, $V_{OUT} = 200\text{ mV}_{PP}$		925		MHz
SSBW	-3 dB Bandwidth	$V_{OUT} = 200\text{ mV}_{PP}$, $R_L = 100\Omega$		730		MHz
SSBW		$V_{OUT} = 200\text{ mV}_{PP}$, $R_L = 150\Omega$		760		
LSBW		$V_{OUT} = 2\text{ V}_{PP}$		560		
0.1 dB BW	0.1 dB Gain Flatness	$V_{OUT} = 200\text{ mV}_{PP}$		270		MHz
Time Domain Response						
TRS	Rise and Fall Time (10% to 90%)	2V Step		0.7		ns
TRL		5V Step		0.8		
SR	Slew Rate	2V Step		3750		V/ μs
t_s	Settling Time to 0.1%	2V Step		10		ns
t_e	Enable Time	From $\overline{\text{Disable}} = \text{Rising Edge}$		10		ns
t_d	Disable Time	From $\overline{\text{Disable}} = \text{Falling Edge}$		15		ns
Distortion						
HD2L	2 nd Harmonic Distortion	2 V_{PP} , 10 MHz		-72		dBc
HD3L	3 rd Harmonic Distortion	2 V_{PP} , 10 MHz		-63		dBc
Equivalent Input Noise						
V_N	Non-Inverting Voltage	>10 MHz		2.1		nV/ $\sqrt{\text{Hz}}$
I_{CN}	Inverting Current	>10 MHz		18.6		pA/ $\sqrt{\text{Hz}}$
N_{CN}	Non-Inverting Current	>10 MHz		26.9		pA/ $\sqrt{\text{Hz}}$
Video Performance						
DG	Differential Gain	4.43 MHz, $R_L = 150\Omega$		0.03		%
DP	Differential Phase	4.43 MHz, $R_L = 150\Omega$		0.03		deg

- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$. No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self heating where $T_J > T_A$. See [Application Information](#) for information on temperature de-rating of this device. Min/Max ratings are based on product characterization and simulation. Individual parameters are tested as noted.
- (2) Limits are 100% production tested at 25C. Limits over the operating temperature range are specified through correlation using Statistical Quality Control (SQC) methods.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.

±5V Electrical Characteristics⁽¹⁾ (continued)

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ\text{C}$, $V^+ = +5\text{V}$, $V^- = -5\text{V}$, $A_V = +2$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ⁽²⁾	Typ ⁽³⁾	Max ⁽²⁾	Units
Static, DC Performance						
V _{IO}	Input Offset Voltage			0.6	2.4 3.4	mV
I _{BN}	Input Bias Current	Non-Inverting	-14 -19	3.5	19 24	μA
PSRR	Power Supply Rejection Ratio	+PSRR	59 59	61.5		dB
		-PSRR	58 58	61		
CMRR	Common Mode Rejection Ratio		53 53	55		dB
XTLK	Crosstalk	Input Referred, f = 10 MHz, Drive Channels A, C and Measure Channel B		-80		dB
I _{CC}	Supply Current	All three amps Enabled, No Load	18 18	19.5	20.8 22	mA
	Supply Current Disabled V ⁺	R _L = ∞		1.54	1.8	mA
	Supply Current Disabled V ⁻	R _L = ∞		0.75	1.8	mA
	Gain Error	R _L = ∞		0.2	1.25	%
	Gain	A _V = +2	1.975	1.996	2.025	V/V
		A _V = +1		0.998		
		A _V = -1	-0.9875	-0.998	-1.0125	
Miscellaneous Performance						
R _{IN} ⁺	Non-Inverting Input Resistance			200		kΩ
C _{IN} ⁺	Non-Inverting Input Capacitance			1		pF
R _O	Output Impedance	DC		0.05		Ω
V _O	Output Voltage Range	R _L = 100Ω	±3.55 ±3.5	±3.7		V
		R _L = ∞	±3.85	±4.0		
CMIR	Input Range	Driving input +INA, CMRR > 40 dB	±3.9 ±3.8	±4.0		V
I _O	Linear Output Current	V _{IN} = 0V, V _{OUT} < ±43 mV ⁽⁴⁾	70	±80		mA
I _{SC}	Short Circuit Current	V _{IN} = 2V Output Shorted to Ground ⁽⁵⁾		237		mA
I _{IH}	Disable Pin Bias Current High	Disable Pin = V ⁺		-72		μA
I _{IL}	Disable Pin Bias Current Low	Disable Pin = 0V		-360		μA
V _{DMAX}	Voltage for Disable	Disable Pin ≤ V _{DMAX}		3.2		V
V _{DMIN}	Voltage for Enable	Disable Pin ≥ V _{DMIN}		3.6		V

- (4) The maximum output current (I_{OUT}) is determined by device power dissipation limitations. See the [POWER DISSIPATION](#) section of the Application Information for more details.
- (5) Short circuit current should be limited in duration to no more than 10 seconds. See the [POWER DISSIPATION](#) section of the Application Information for more details.

Typical Performance Characteristics $V^+ = +5V$

($T_A = 25^\circ\text{C}$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

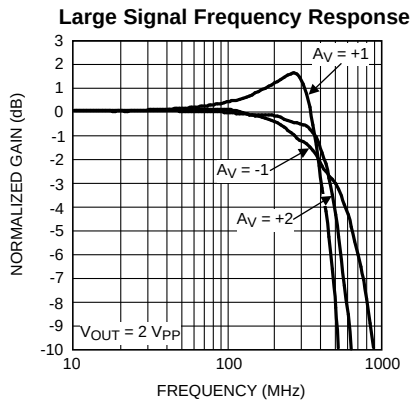


Figure 2.

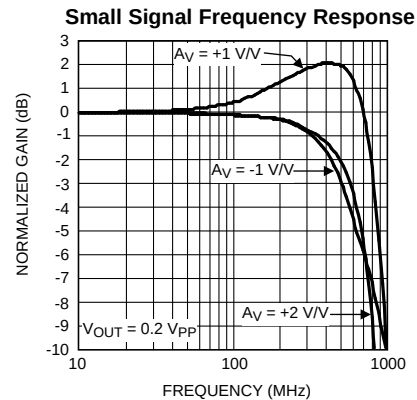


Figure 3.

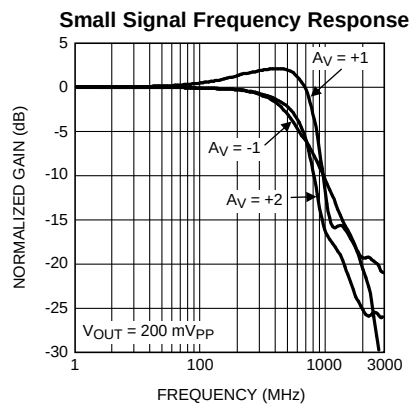


Figure 4.

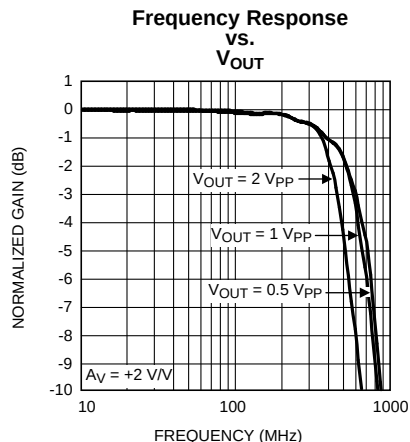


Figure 5.

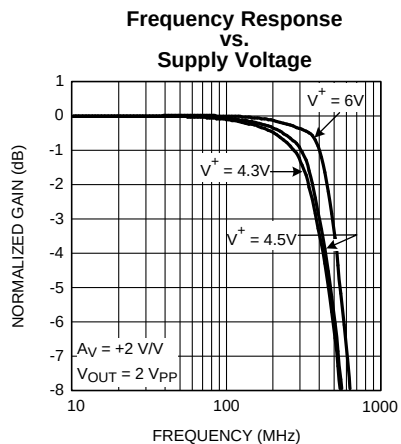


Figure 6.

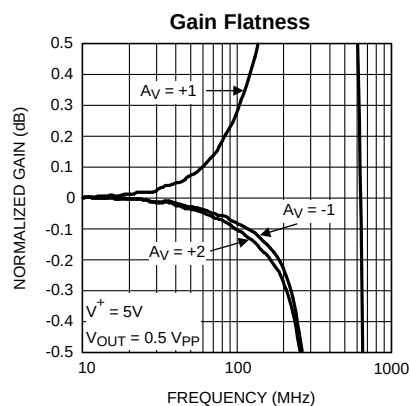


Figure 7.

Typical Performance Characteristics $V^+ = +5V$ (continued)

($T_A = 25^\circ C$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

Gain Flatness, Dual Input Buffer

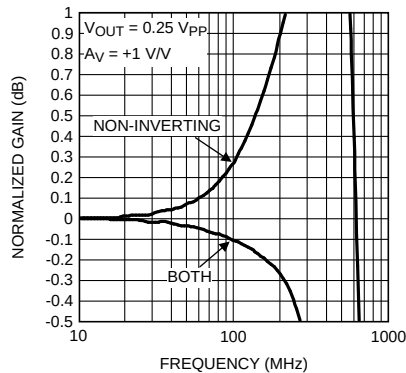


Figure 8.

Pulse Response

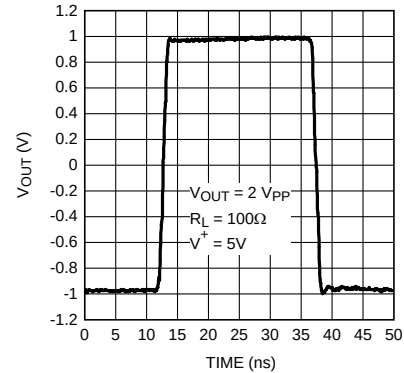


Figure 9.

**Crosstalk
vs.
Frequency**

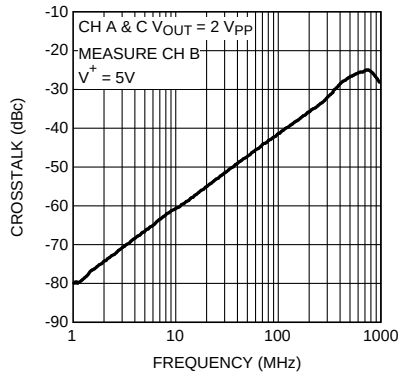


Figure 10.

**Distortion
vs.
Frequency**

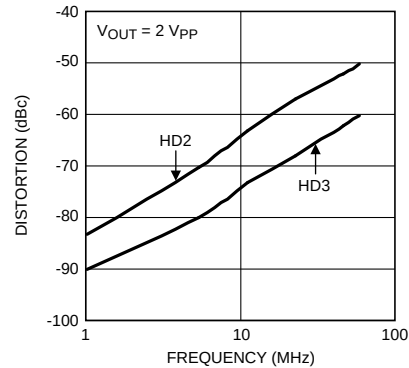


Figure 11.

**Distortion
vs.
Output Voltage**

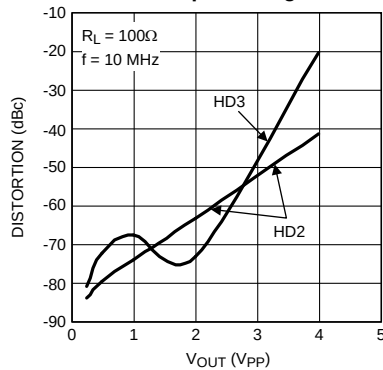


Figure 12.

**Small Signal Frequency Response
vs.
Resistive Load**

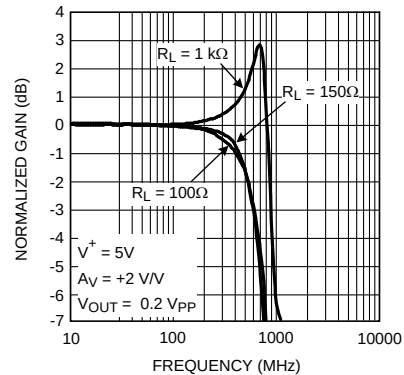


Figure 13.

Typical Performance Characteristics $V^+ = +5V$ (continued)

($T_A = 25^\circ\text{C}$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

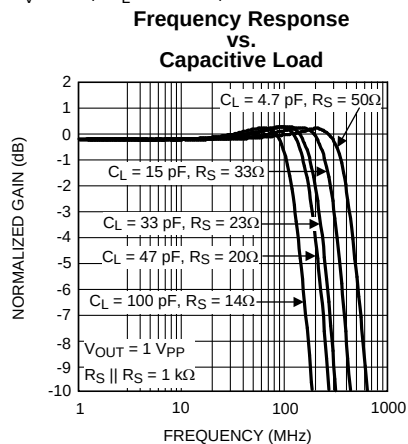


Figure 14.

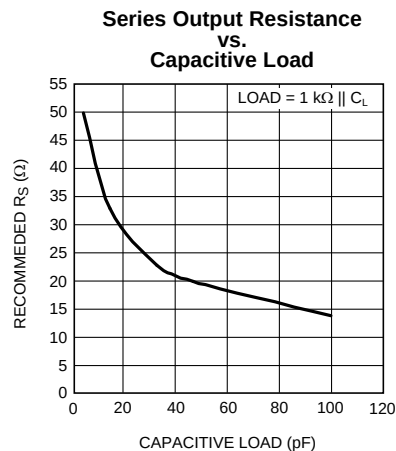


Figure 15.

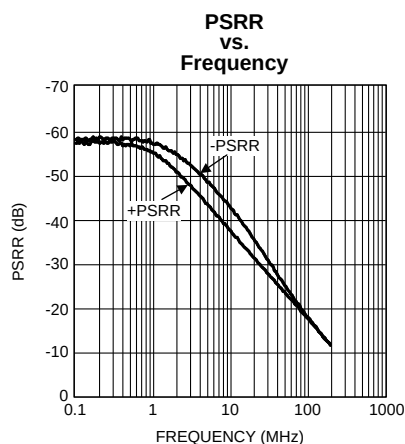


Figure 16.

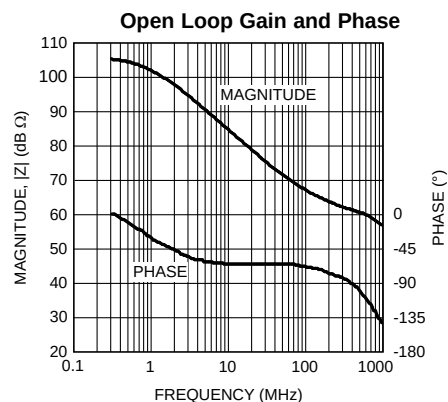


Figure 17.

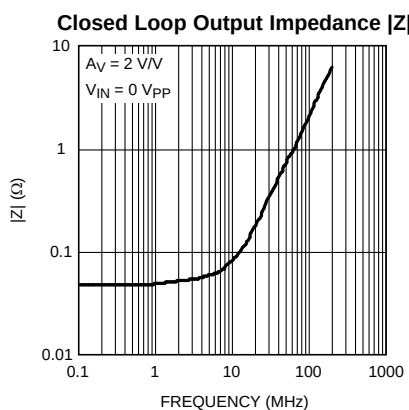


Figure 18.

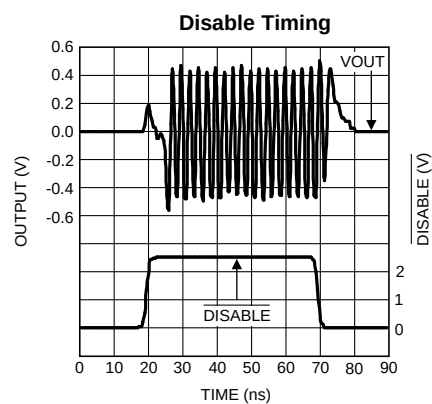


Figure 19.

Typical Performance Characteristics $V^+ = +5V$ (continued)

($T_A = 25^\circ\text{C}$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

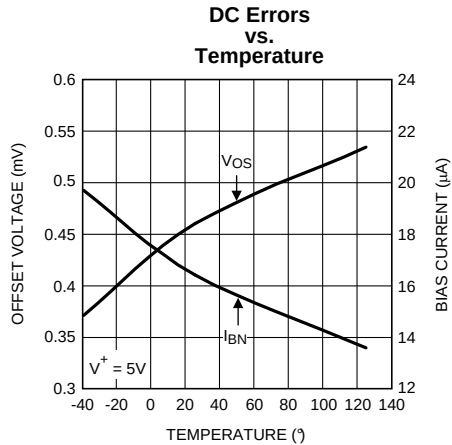


Figure 20.

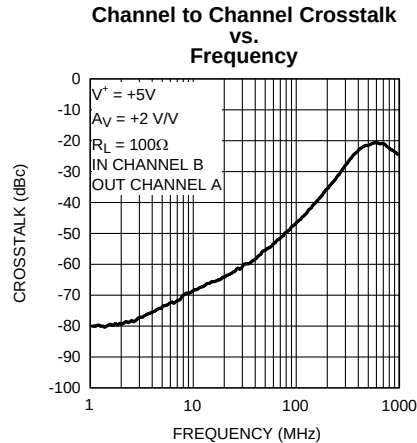


Figure 21.

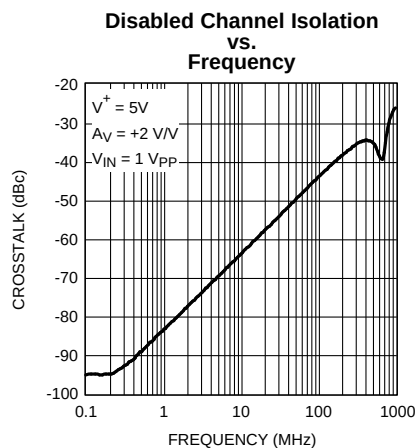


Figure 22.

Typical Performance Characteristics $V^+ = +5V$, $V^- = -5V$

($T_A = 25^\circ\text{C}$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

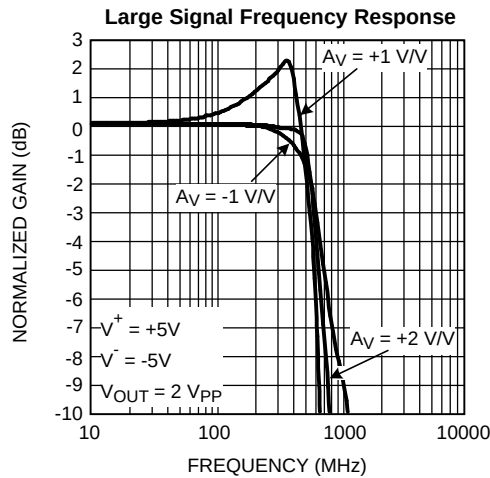


Figure 23.

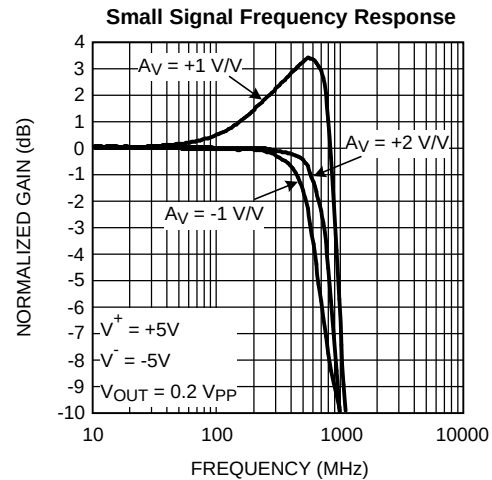


Figure 24.

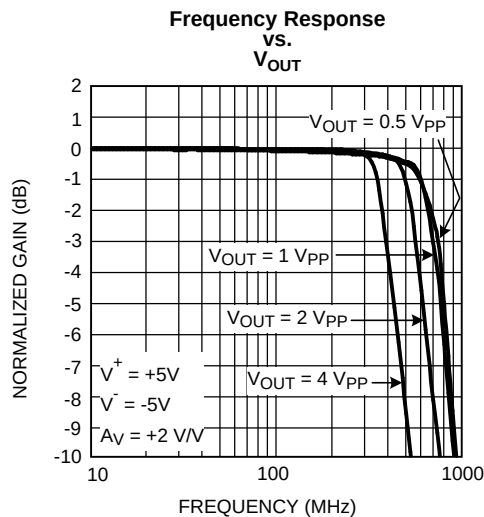


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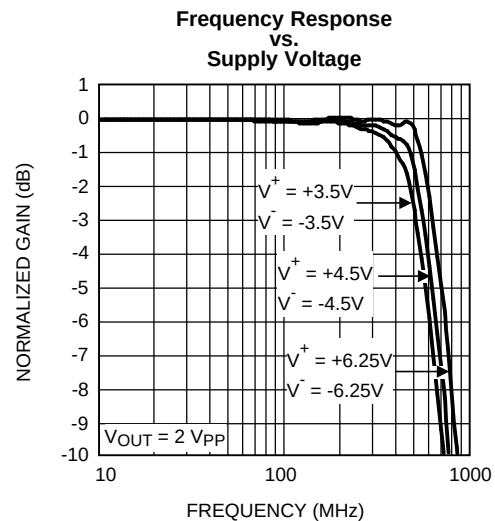


Figure 26.

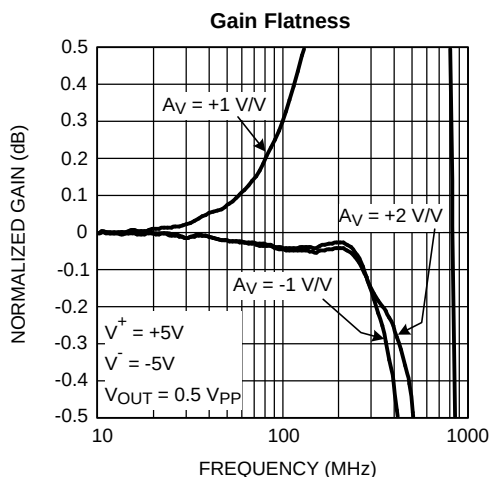


Figure 27.

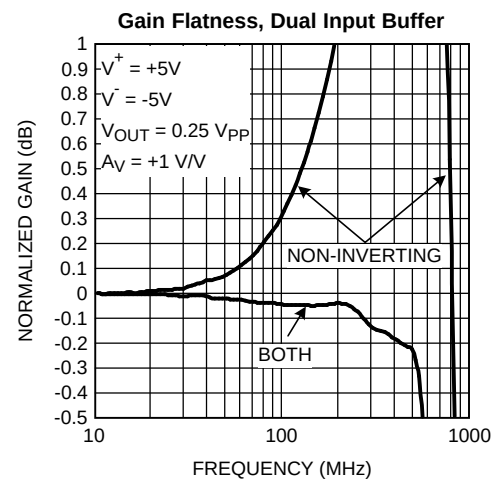


Figure 28.

Typical Performance Characteristics $V^+ = +5V$, $V^- = -5V$ (continued)

($T_A = 25^\circ\text{C}$, $A_V = +2$, $R_L = 100\Omega$, unless otherwise specified.)

Pulse Response

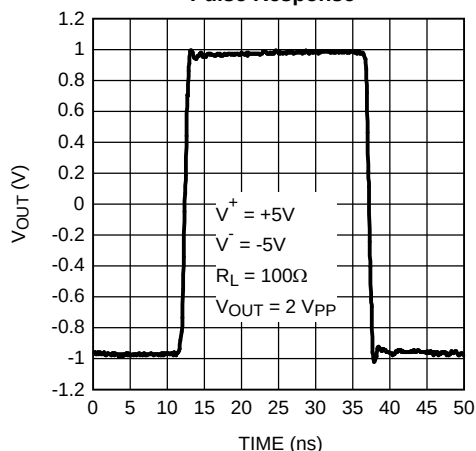


Figure 29.

Pulse Response

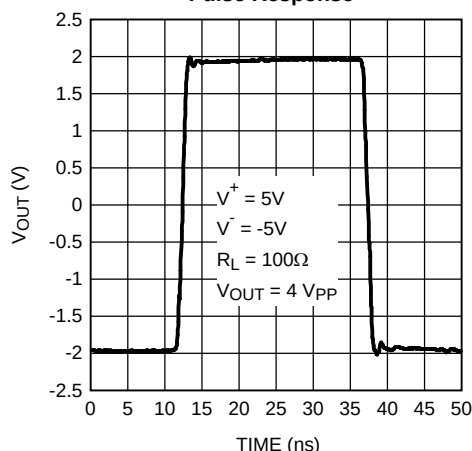


Figure 30.

Distortion
vs.
Frequency

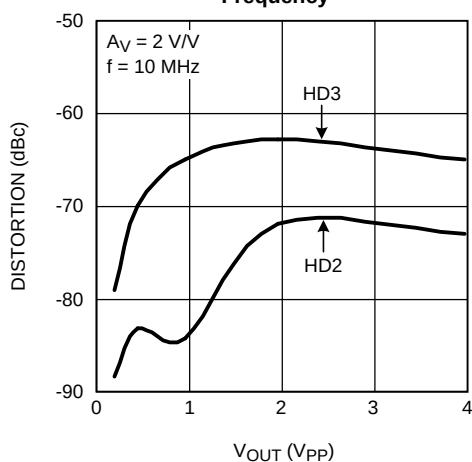


Figure 31.

Distortion
vs.
Output Voltage

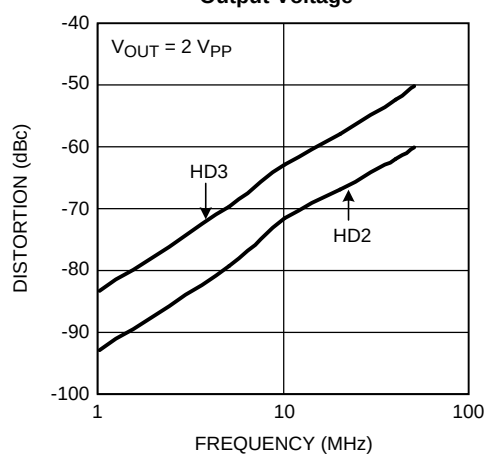


Figure 32.

DC Errors
vs.
Temperature

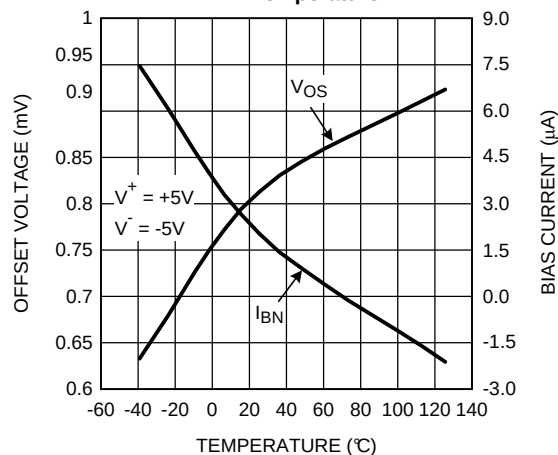


Figure 33.

Crosstalk
vs.
Frequency

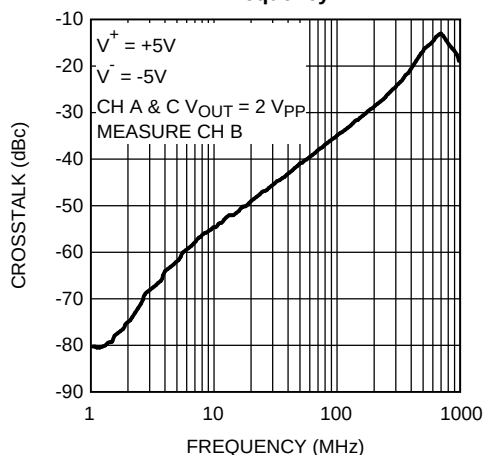


Figure 34.

APPLICATION INFORMATION

GENERAL INFORMATION

The LMH6734 is a high speed current feedback selectable gain buffer (SGB), optimized for very high speed applications. With its internal feedback and gain-setting resistors, $R_F = R_G = 327\Omega$, the LMH6734 offers excellent AC performance while simplifying board layout and minimizing the effects of layout related parasitic components. The LMH6734 has no internal ground reference so single or split supply configurations are both equally useful.

SETTING THE CLOSED LOOP GAIN

The LMH6734 can be configured with gain settings of $A_V = +2$, $+1$, or -1 . [Table 1](#) shows the non-inverting and inverting pin connections to achieve the desired closed loop gain.

Table 1. Setting the Closed Loop Gain

GAIN A_V	INPUT CONNECTIONS	
	Non-Inverting	Inverting
-1 V/V	Ground	Input Signal
+1 V/V	Input Signal	NC (Open)
+2 V/V	Input Signal	Ground

SPLIT SUPPLY APPLICATION

The recommended split supply circuit applications are shown in [Figure 35](#), [Figure 36](#), and [Figure 37](#). In all three configurations the input signal is DC coupled with a termination resistor input $R_{IN} = 50\Omega$. In [Figure 35](#) the inverting input is connected to ground completing the internal feedback loop to set the gain to $+2$ V/V. In [Figure 36](#) the inverting input is open (no-connect), thus providing a buffer configuration of $+1$ V/V. [Figure 37](#) shows a buffer configuration with a gain of -1 V/V. In this configuration an input resistor of 59Ω was used to balance the internal R_G resistor of 327Ω and to provide a 50Ω termination.

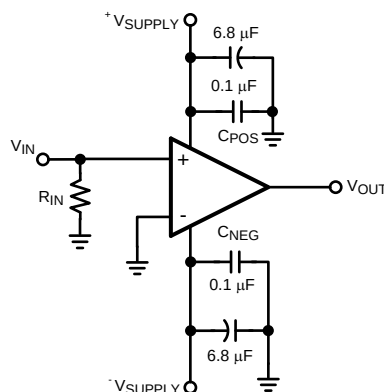


Figure 35. Recommended Split Supply Non-Inverting Gain Circuit, Gain = $+2$ V/V

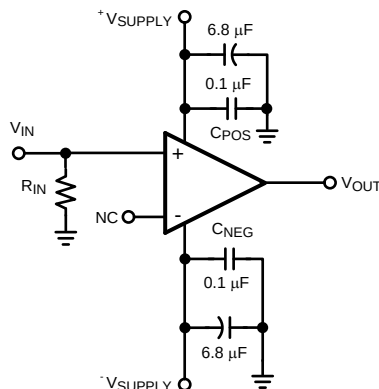


Figure 36. Recommended Split Supply Non-Inverting Gain Circuit, Gain +1 V/V

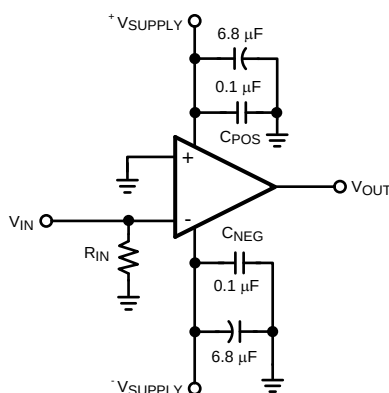


Figure 37. Recommended Split Supply Inverting Gain Circuit, Gain = -1 V/V

SINGLE SUPPLY APPLICATION

The LMH6734 can also be configured for single supply applications as shown in [Figure 38](#), [Figure 39](#), and [Figure 40](#). In [Figure 38](#), the 220 μF capacitor was chosen to satisfy low frequency input signals and to provide an open for the internal feedback network path, thus setting the gain to +1 V/V. With an AC signal present, this 220 μF capacitor is shunted to ground and completes the feedback resistor network to set the AC coupled gain of +2 V/V. The input is AC coupled with the 22 μF capacitor and the two 4.7 k Ω resistors to set the input DC bias voltage. [Figure 39](#) shows the single supply buffer configuration with the inverting input open (no-connect) creating an open to the internal feedback network giving a gain of +1 V/V. The input voltage is AC coupled with the 22 μF capacitor along with two 4.7 k Ω resistors to set the input DC bias voltage. [Figure 40](#) shows the single supply buffer configuration for a gain of -1 V/V. In this circuit, the input signal is DC coupled into the inverting input closing the internal feedback network and creating a gain of -1 V/V while an AC gain of +2 V/V is present at the non-inverting input. Thus, the 6.8 k Ω and the 2.2 k Ω resistors were chosen to set the input DC bias voltage to 1/4 the supply voltage such that at high frequencies the output voltage is gained up by +2 V/V.

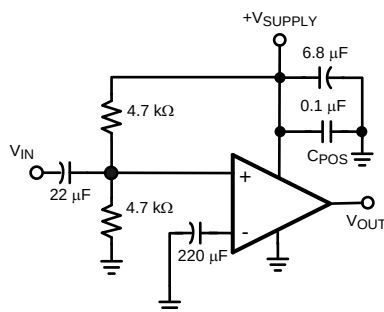


Figure 38. Recommended Single Supply Non-Inverting Gain Circuit, Gain = +2 V/V

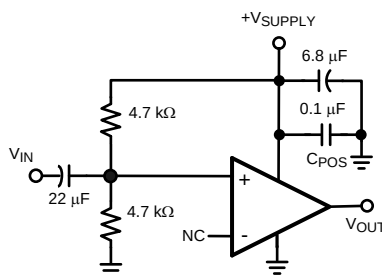


Figure 39. Recommended Single Supply Non-Inverting Gain Circuit, Gain = +1 V/V

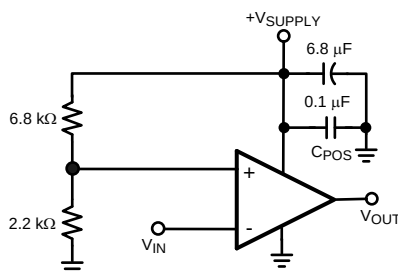


Figure 40. Recommended Single Supply Inverting Gain Circuit, Gain = -1 V/V

The gain of the LMH6734 is accurate to $\pm 1\%$ and stable over temperature. The internal gain setting resistors, R_F and R_G , match very well. However, over process and temperature their absolute value will change. Using external resistors in series with R_G to change the gain will result in poor gain accuracy over temperature and from part to part.

UNITY GAIN COMPENSATION

With a current feedback Selectable Gain Buffer like the LMH6734, the feedback resistor is a compromise between the value needed for stability at unity gain and the optimized value used at a gain of two. The result of this compromise is substantial peaking at unity gain. If this peaking is undesirable a simple RC filter at the input of the buffer will smooth the frequency response as shown in Figure 41. Figure 42 shows the results of a simple filter placed on the non-inverting input. See Figure 43 and Figure 44 for another method of reducing unity gain peaking.

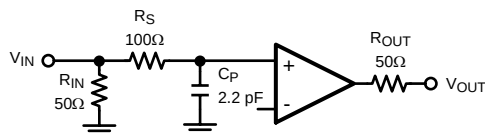


Figure 41. Correction for Unity Gain Peaking

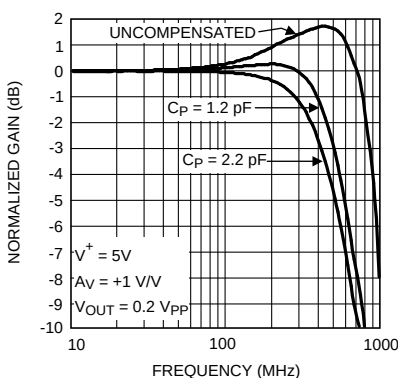


Figure 42. Frequency Response for Circuit in Figure 41

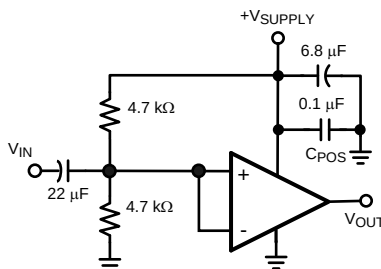


Figure 43. Alternate Unity Gain Compensation

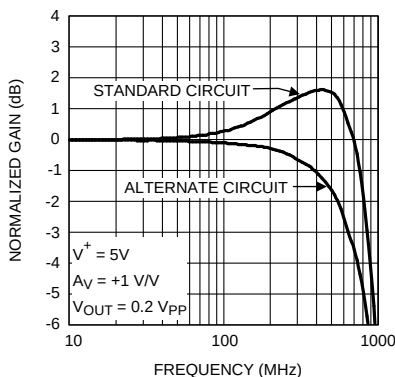


Figure 44. Frequency Response for Circuit in Figure 43 (Standard Circuit Figure 39)

COMPONENT DRIVER

The LMH6734 is capable of transmitting and receiving component video over short to moderate unshielded twisted-pair (UTP) CAT5 cables, as shown in Figure 45. The component signals Y, Pb, and Pr are connected to the LMH6734 transmit side inputs with a 75Ω termination. The LMH6734 transmit amplifiers are configured for a gain of +2 V/V before driving the CAT5 cable. Only three out of the four pairs in the standard CAT5 are utilized, the fourth pair is available for audio. The output of the LMH6734 transmit amplifier drives a 50Ω transmission system with one side of the twisted pair terminated 50Ω to ground. Note this system, without signal equalization, will satisfy transmission up to 200 ft. For longer cable lengths, frequency and gain equalization to compensate for signal degradation is recommended.

The LMH6734 receive side is configured for a unity gain buffer for the component signals received through the CAT5 cable. The inputs of the receiver channels are 100Ω differentially terminated. The two 327Ω external resistors were chosen to match the internal R_F and R_G value of 327Ω. Figure 46, shows the LMH6734 transceiver frequency response over various lengths of CAT5 cable with a 1 V_{PP} input signal at ±5 supply voltage. The CMRR of the LMH6734 receive side at low frequencies is 55 dB at best with a split power supply of ±5V.

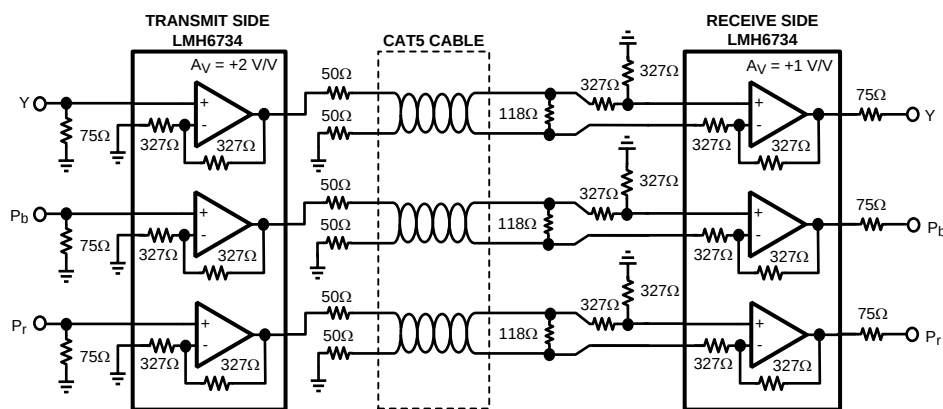


Figure 45. Component Video Transmission Over UTP (CAT5)

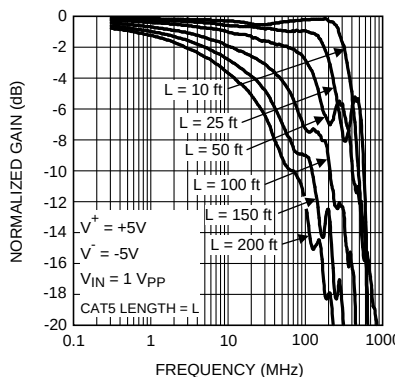


Figure 46. Frequency Response vs. Normalized Gain and CAT5 Cable Length

DRIVING CAPACITIVE LOADS

Capacitive output loading applications will benefit from the use of a series output resistor R_{OUT} . Figure 47 shows the use of a series output resistor, R_{OUT} , to stabilize the amplifier output under capacitive loading. Capacitive loads of 5 to 120 pF are the most critical, causing ringing, frequency response peaking and possible oscillation. The charts “Suggested R_{OUT} vs. Cap Load” give a recommended value for selecting a series output resistor for mitigating capacitive loads. The values suggested in the charts are selected for 0.5 dB or less of peaking in the frequency response. This gives a good compromise between settling time and bandwidth. For applications where maximum frequency response is needed and some peaking is tolerable, the value of R_{OUT} can be reduced slightly from the recommended values.

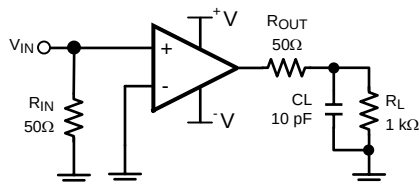


Figure 47. Decoupling Capacitive Loads

LAYOUT CONSIDERATIONS

Whenever questions about layout arise, use the evaluation board as a guide. The LMH730275 is the evaluation board supplied with samples of the LMH6734.

To reduce parasitic capacitances, ground and power planes should be removed near the input and output pins. For long signal paths controlled impedance lines should be used, along with impedance matching elements at both ends.

Bypass capacitors should be placed as close to the device as possible. Bypass capacitors from each rail to ground are applied in pairs. The larger electrolytic bypass capacitors can be located farther from the device, the smaller ceramic capacitors should be placed as close to the device as possible. The LMH6734 has multiple power and ground pins for enhanced supply bypassing. Every pin should ideally have a separate bypass capacitor. Sharing bypass capacitors may slightly degrade second order harmonic performance, especially if the supply traces are thin and /or long. In Figure 35, Figure 36, and Figure 37 it is recommended an optional capacitor, C_{SS} = 0.01 μ F, be connected between the split supplies for best second harmonic distortion. Another option to using C_{SS} is to use pairs of 0.01 μ F and 0.1 μ F ceramic capacitors for each supply bypass.

VIDEO PERFORMANCE

The LMH6734 has been designed to provide excellent performance with production quality video signals in a wide variety of formats such as HDTV and High Resolution VGA. NTSC and PAL performance is nearly flawless. Best performance will be obtained with back terminated loads. The back termination reduces reflections from the transmission line and effectively masks transmission line and other parasitic capacitances from the amplifier output stage. [Figure 41](#) shows a typical configuration for driving a 75Ω cable. The amplifier is configured for a gain of two to make up for the 6 dB of loss in R_{OUT} .

POWER DISSIPATION

The LMH6734 is optimized for maximum speed and performance in the small form factor of the standard 16-Pin SSOP package. To achieve its high level of performance, the LMH6734 consumes an appreciable amount of quiescent current which cannot be neglected when considering the total package power dissipation limit. The quiescent current contributes to about 40° C rise in junction temperature when no additional heat sink is used ($V_S = \pm 5V$, all three channels on). Therefore, it is easy to see the need for proper precautions in order to make sure the junction temperature's absolute maximum rating of 150°C is not violated.

To ensure maximum output drive and highest performance, thermal shutdown is not provided. Therefore, it is of utmost importance to make sure that the T_{JMAX} is never exceeded due to the overall power dissipation (all three channels).

With the LMH6734 used in a back-terminated 75Ω RGB analog video system (with 2 V_{PP} output voltage), the total power dissipation is around 305 mW of which 220 mW is due to the quiescent device dissipation (output black level at 0V). With no additional heat sink used, the junction temperature rises to about 120°C when operated at 85°C ambient.

To reduce the junction temperature many options are available. Forced air cooling is the easiest option. An external add-on heat-sink can be added to the 16-Pin SSOP package, or alternatively, additional board metal (copper) area can be utilized as heat-sink.

An effective way to reduce the junction temperature for the 16-Pin SSOP package (and other plastic packages) is to use the copper board area to conduct heat. With no enhancement the major heat flow path in this package is from the die through the metal lead frame (inside the package) and onto the surrounding copper through the interconnecting leads. Since high frequency performance requires limited metal near the device pins the best way to use board copper to remove heat is through the bottom of the package. A gap filler with high thermal conductivity can be used to conduct heat from the bottom of the package to copper on the circuit board. Vias to a ground or power plane on the back side of the circuit board will provide additional heat dissipation. A combination of front side copper and vias to the back side can be combined as well.

Follow these steps to determine the maximum power dissipation for the LMH6734:

1. Calculate the quiescent (no-load) power: $P_{AMP} = I_{CC} \times (V_S)$ $V_S = V^+ - V^-$
2. Calculate the RMS power dissipated in the output stage:
 - $P_D (rms) = rms ((V_S - V_{OUT}) \times I_{OUT})$ where V_{OUT} and I_{OUT} are the voltage and current across the external load and V_S is the total supply current
3. Calculate the total RMS power: $P_T = P_{AMP} + P_D$

The maximum power that the LMH6734 package can dissipate at a given temperature (See [Figure 48](#)) can be derived with the following equation:

$P_{MAX} = (150^\circ C/W - T_{AMB}) / \theta_{JA}$, where T_{AMB} = Ambient temperature (°C) and θ_{JA} = Thermal resistance, from junction to ambient, for a given package (°C/W). For the SSOP package θ_{JA} is 120°C/W.

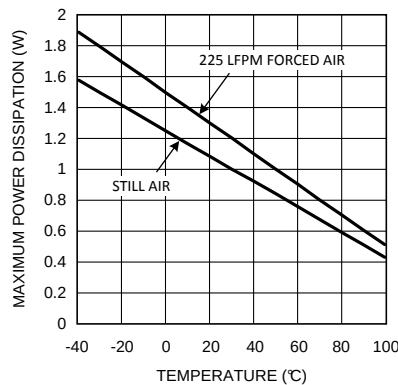


Figure 48. Maximum Power Dissipation

ESD PROTECTION

The LMH6734 is protected against electrostatic discharge (ESD) on all pins. The LMH6734 will survive 2000V Human Body Model and 200V Machine Model events.

Under closed loop operation the ESD diodes have no affect on circuit performance. There are occasions, however, when the ESD diodes will be evident. If the LMH6734 is driven by a large signal while the device is powered down the ESD diodes will conduct.

The current that flows through the ESD diodes will either exit the chip through the supply pins or will flow through the device, hence it is possible to power up a chip with a large signal applied to the input pins. Shorting the power pins to each other will prevent the chip from being powered up through the input.

EVALUATION BOARDS

Texas Instruments provides the following evaluation boards as a guide for high frequency layout and as an aid in device testing and characterization. Many of the datasheet plots were measured with these boards.

Device	Package	Evaluation Board Part Number
LMH6734MQ	SSOP	LMH730275

A bare evaluation board can be ordered when a sample request is placed with Texas Instruments.

REVISION HISTORY

Changes from Revision B (April 2013) to Revision C

Page

- Changed layout of National Data Sheet to TI format [19](#)

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